

Handlers in Action

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Programming with effects

Implicit effects

```
# let f = fun x -> let y = ! loc in  
                    loc := x + y;;  
val f : int -> unit = <fun>
```

```
# let g = fun i -> if (i < 0)  
                  then raise (Failure "neg.")  
                  else 0;;  
val g : int -> int = <fun>
```

Trivially combined

```
# let h = f(7); g(1);;  
val h : int = 0
```

Controlling effects: effect systems

```
val f : int  $\xrightarrow{\{lookup, update\}}$  unit = <fun>
```

```
val g : int  $\xrightarrow{\{raise\}}$  int = <fun>
```

```
val h : int ! {lookup, update, raise}
```

Rigid effects

Fixed collection of effects.

Explicit effects

```
f :: Int -> State Int ()  
f = \ x -> do { y <- get;  
              put (x+y) }
```

```
g :: Int -> ErrorT String Identity Int  
g = \ i -> if (i < 0)  
          then throwError "neg."  
          else return 0
```

Sophisticated combination

```
f :: Int -> State Int ()  
f = \ x -> do { y <- get;  
              put (x+y) }
```

```
g :: Monad m => Int -> ErrorT String m Int  
g = \ i -> if (i < 0)  
          then throwError "neg."  
          else return 0
```

```
h :: (ErrorT String (State Int)) Int  
h = do { lift (f 7);  
        g 0 }
```

Controlling effects: Monads

```
f :: Int -> State Int ()
```

```
g :: Monad m => Int -> ErrorT String m Int
```

```
h :: (ErrorT String (State Int)) Int
```

Manual/semi-inferred, intrinsic.

Fluid effects

User defined effects.

Layered monads and effect reification

Monads in action, Filinski, POPL'10.

Eff

Programming with algebraic effects and handlers, Bauer and Pretnar, arXiv draft, 2012.

Idea

- ▶ Operational semantics for an Eff variant.
- ▶ Inspired by Filinski.

Contribution

The λ_{eff} -calculus:

- ▶ Implicit effects.
- ▶ Trivially combined.
- ▶ Fluidity.

Non-contribution

Controlling effects: type system, effect system.

- ▶ Running example: pipes.
- ▶ λ_{eff} -calculus
- ▶ Pipes: implementation and execution.
- ▶ Summary and further work.

Running example: pipes

```
M1 = x ← random(2);  
    if (x = 1)  
    then put('y')  
    else put('n');  
    put('\n')
```

```
M2 = s ← readln;  
    if (s = "y")  
    then set(loc, 10);
```

M1 | M2

No concurrency!

Syntax

$$\begin{aligned}
 V &::= x \mid * \mid \mathbf{thunk} \ M \\
 M, N &::= \mathbf{return} \ V \mid x \leftarrow M_1; M_2 \mid \mathbf{force} \ V \mid \\
 &\quad \lambda x. M \mid M \ V \mid \mathit{op}(V)(\lambda x. M) \mid \\
 &\quad \mathbf{whatever} \ V \mid \mathbf{handle} \ M \ \mathbf{with} \ H \\
 H &::= \mathbf{handler} \ \{ \mathbf{return} \ : \ M_{\text{ret}} \\
 &\quad \mathit{op}_1 \quad \quad : \ N_1 \\
 &\quad \dots \\
 &\quad \mathit{op}_n \quad \quad : \ N_n \}
 \end{aligned}$$

For example,

abbreviated as

<code>output('a')(λ_. return *)</code>	<code>put('a')</code>
<code>input(*) (λc. return c)</code>	<code>get</code>
<code>raise("neg.")(λz. whatever z)</code>	<code>raise("neg.")</code>

Base case:

```
handle return 'a'  
with handler {return:  $\lambda c. put(c)$ }  
   $\rightarrow (\lambda c. put(c)) 'a' \rightarrow put('a')$ 
```

Generally:

```
handle return  $V$  with handler {return:  $N_{ret} \dots$ }  
   $\rightarrow N_{ret} V$ 
```

Operations

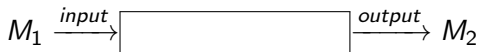
$H := \text{handler } \{ \text{return} : \lambda x. \text{return } x$
 $\quad \text{input} : \lambda_. \lambda k. (\text{force } k) \text{ 'f'} \}$

$\text{handle } \text{input} (*) (\lambda c. \text{return } c) \text{ with } H$
 $\longrightarrow (\lambda_. \lambda k. (\text{force } k) \text{ 'f'})$
 $\quad * (\text{thunk } \lambda c. \text{handle } \text{return } c \text{ with } H)$
 $\longrightarrow (\lambda k. (\text{force } k) \text{ 'f'})$
 $\quad (\text{thunk } \lambda c. \text{handle } \text{return } c \text{ with } H)$
 $\longrightarrow (\text{force } (\text{thunk } (\lambda c. \text{handle } \text{return } c \text{ with } H)))$
 $\quad \text{'f'}$
 $\longrightarrow \text{handle } \text{return } \text{'f'} \text{ with } H$
 $\longrightarrow \text{return } \text{'f'}$

Operations

Generally, given:

$$H := \mathbf{handler} \left\{ \begin{array}{ll} \mathbf{return} & : M_{\text{ret}} \\ op_1 & : N_1 \\ \dots & \\ op_n & : N_n \end{array} \right\}$$
$$\mathbf{handle} \ op_i(V)(\lambda x. M) \ \mathbf{with} \ H \\ \longrightarrow N_i \ V \ (\mathbf{thunk} \ \lambda x. \mathbf{handle} \ M \ \mathbf{with} \ H)$$



Idea

- ▶ Parametrise M_2 by a computation **producing** characters, and
 - ▶ parametrise M_1 by a computation **consuming** characters,
- without touching M_1 , M_2 .

$$H_2 := \text{handler } \left\{ \begin{array}{l} \text{return} : \lambda x. \lambda \text{prod}. \text{return } x \\ \text{input} : \lambda _ . \lambda k. \lambda \text{prod}. \\ \quad (\text{force prod}) * k \end{array} \right\}$$
$$H_1 := \text{handler } \left\{ \begin{array}{l} \text{return} : \lambda z. \text{whatever } z \\ \text{output} : \lambda c. \lambda k. \lambda \text{cons}. \\ \quad (\text{force cons}) c k \end{array} \right\}$$
$$M_1 \mid M_2 := \text{handle } M_2 \text{ with } H_2 \\ (\text{thunk } \lambda _ . \text{handle } M_1 \text{ with } H_1)$$

Run $M_1 \mid M_2$ for:

$$M_1 := \text{output}('a')(\lambda _ . M'_1) \\ M_2 := \text{input} (*)(\lambda c. M'_2 c)$$

$$M_1 \mid M_2 =$$

```

handle input (*) ( $\lambda c. M'_2$  c)
with handler {return:  $\lambda x. \lambda \text{prod}. \text{return } x$ 
                input :  $\lambda_. \lambda k. \lambda \text{prod}.
                        (\text{force } \text{prod}) * k$ }
  (thunk  $\lambda_. \text{handle } M_1 \text{ with } H_1$ )
→
( $\lambda_. \lambda k. \lambda \text{prod}. (\text{force } \text{prod}) * k$ )
*
(thunk  $\lambda c. \text{handle } M'_2 \text{ } c \text{ with } H_2$ )
(thunk  $\lambda_. \text{handle } M_1 \text{ with } H_1$ )

```

\rightarrow^3
(force (thunk $\lambda_.$ handle M_1 with H_1))

(thunk ($\lambda c.$ thunk handle M'_2 c with H_2))
 \rightarrow
($\lambda_.$ handle M_1 with H_1)

(thunk ($\lambda c.$ thunk handle M'_2 c with H_2))
 \rightarrow
handle M_1 with H_1
(thunk ($\lambda c.$ handle M'_2 c with H_2))

```
=  
handle output('a')(λ-.M'1)  
with handler {return: λz.whatever z  
               output: λc.λk.λcons.  
                       (force cons) c k}  
(think (λc.handle M'2 c with H2))  
→  
(λc.λk.λcons.(force cons) c k)  
'a'  
(think λ-.handle M'1 with H1)  
(think (λc.handle M'2 c with H2))
```

$$\begin{aligned}
 &\longrightarrow^3 \\
 &(\mathbf{force} \ (\mathbf{thunk} \ (\lambda c. \mathbf{handle} \ M'_2 \ c \ \mathbf{with} \ H_2))) \\
 &\quad \mathbf{'a'}$$

$$\begin{aligned}
 &\quad (\mathbf{thunk} \ \lambda_. \mathbf{handle} \ M'_1 \ \mathbf{with} \ H_1) \\
 &\longrightarrow \\
 &(\lambda c. \mathbf{handle} \ M'_2 \ c \ \mathbf{with} \ H_2) \\
 &\quad \mathbf{'a'}$$

$$\begin{aligned}
 &\quad (\mathbf{thunk} \ \lambda_. \mathbf{handle} \ M'_1 \ \mathbf{with} \ H_1) \\
 &\longrightarrow \\
 &\mathbf{handle} \ M'_2 \ \mathbf{'a' with} \ H_2 \\
 &\quad (\mathbf{thunk} \ \lambda_. \mathbf{handle} \ M'_1 \ \mathbf{with} \ H_1) \\
 &= \\
 &M'_1 \mid (M'_2 \ \mathbf{'a'})
 \end{aligned}$$

Expected behaviour

$$\begin{array}{l} \text{output('a')}(\lambda_.M'_1) \mid (\text{input } (*))(\lambda c.M'_2 \ c) \\ \longrightarrow^* \\ M'_1 \mid (M'_2 \ 'a') \end{array}$$

Unhandled effects

$$H := \text{handler } \left\{ \begin{array}{ll} \text{return} & : M_{\text{ret}} \\ op_1 & : N_1 \\ \dots & \\ op_n & : N_n \end{array} \right\}$$

If $\boxed{op} \notin \{op_1, \dots, op_n\}$ then:

$$\begin{aligned} & \text{handle } \boxed{op}(V)(\lambda x.M) \text{ with } H \\ & \longrightarrow \boxed{op}(V)(\lambda x.\text{handle } M \text{ with } H) \end{aligned}$$

i.e., implicit handling:

$$\begin{aligned} & \text{handler } \{ \dots \\ & \quad \boxed{op} : \lambda p.\lambda k.\boxed{op}(p)(\lambda x.(\text{force } k) x) \\ & \quad \dots \} \end{aligned}$$

Further work

- ▶ Type system, type inference.
- ▶ Effect reification.
- ▶ Implement as Haskell, ML, Scheme libraries?
- ▶ What is the delta? (e.g., delimited continuations? proof obligations?)

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