

Take Action for Your State

Effective Conservative Restrictions

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A Tale of Three Monads...

State (S a set):

$$A \mapsto S \rightarrow (S \times A)$$

$$T \mapsto S \rightarrow T(S \times -)$$

Reader (S a set):

$$A \mapsto S \rightarrow A$$

$$T \mapsto S \rightarrow T(-)$$

Writer (M a monoid):

$$A \mapsto M \times A$$

$$T \mapsto T(M \times -)$$

Some underlying common structure?

Investigation

- ▶ View through Algebraic Theory of Effects.
- ▶ Generalise using monoid actions.
- ▶ Borrow ideas from our work on type and effect systems.
- ▶ Describe underlying structure.

Interface vs. Implementation

Signature $\langle \Sigma, : \rangle$:

Set Σ of *function symbols* and an *arity* function $(:) : \Sigma \rightarrow \mathbb{N}$.

Theory/Presentation $\langle \Sigma, E \rangle$:

Signature Σ with a set of *equations* $E \subseteq \Sigma\text{-Terms} \times \Sigma\text{-Terms}$.

Monoids:

Signature:

$$(\cdot) : 2$$

$$e : 0$$

Equations:

$$(x \cdot y) \cdot z = x \cdot (y \cdot z)$$

$$x \cdot e = e \cdot x = x$$

Some Universal Algebra

Lawvere theory:

Essentially the quotient: Σ -Terms / E .

Model $\langle M, \llbracket - \rrbracket \rangle$:

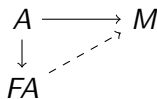
Set M and an interpretation of the terms as M -operations.

Free model FA :

Universal property:

All $A \rightarrow M$ extend uniquely to $FA \rightarrow M$.

Amounts to the quotient Σ -Terms(A)/ E .



Some Category Theory

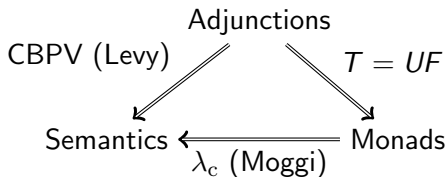
Forgetful Functor:

$$U : \langle M, \llbracket - \rrbracket \rangle \mapsto M$$

Free Model Adjunction:

$$F \dashv U$$

Semantics



Algebraic Theory of Effects

operations, presentations



Lawvere theories



adjunctions

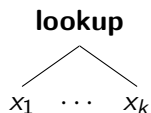


monads

Global State Operations

For a set of states S , $|S| = k > 0$:

lookup : $|S|$



lookup($\lambda s.x_s$)

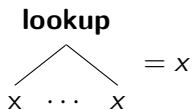
upd_S : 1



upd_S x

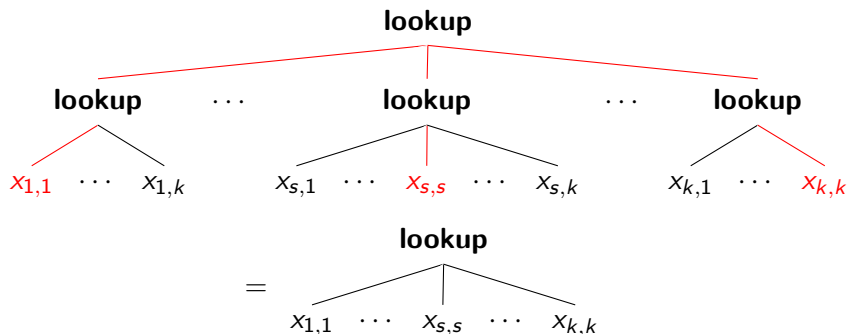
Global State Presentation

lookup $(\lambda s.x) = x$



Global State Presentation

lookup ($\lambda s.x$) = x **lookup** ($\lambda s. \text{lookup} (\lambda t.x_{s,t})$) = **lookup** ($\lambda r.x_{r,r}$)



Global State Presentation

lookup ($\lambda s.x$) = x **lookup** ($\lambda s. \text{lookup} (\lambda t.x_{s,t})$) = **lookup** ($\lambda r.x_{r,r}$)

upd_s (**upd_t** x) = **upd_t** x

Global State Presentation

lookup $(\lambda s.x) = x$ **lookup** $(\lambda s.\text{lookup}(\lambda t.x_{s,t})) = \text{lookup}(\lambda r.x_{r,r})$

upd_s $(\text{upd}_t x) = \text{upd}_t x$ **upd_s lookup** $(\lambda s.x_s) = \text{upd}_s x_s$

Global State Presentation

lookup $(\lambda s.x) = x$ **lookup** $(\lambda s.\text{lookup}(\lambda t.x_{s,t})) = \text{lookup}(\lambda r.x_{r,r})$

upd_s $(\text{upd}_t x) = \text{upd}_t x$ **upd_s** **lookup** $(\lambda s.x_s) = \text{upd}_s x_s$

lookup $(\lambda s.\text{upd}_s x_s) = \text{lookup}(\lambda s.x_s)$

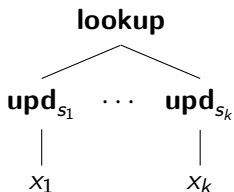
Global State Free Model Monad

$$\mathbf{lookup} (\lambda s. x) = x \quad \mathbf{lookup} (\lambda s. \mathbf{lookup} (\lambda t. x_{s,t})) = \mathbf{lookup} (\lambda r. x_{r,r})$$

$$\mathbf{upd}_s (\mathbf{upd}_t x) = \mathbf{upd}_t x \quad \mathbf{upd}_s \mathbf{lookup} (\lambda s. x_s) = \mathbf{upd}_s x_s$$

$$\mathbf{lookup} (\lambda s. \mathbf{upd}_s x_s) = \mathbf{lookup} (\lambda s. x_s)$$

Normal form:

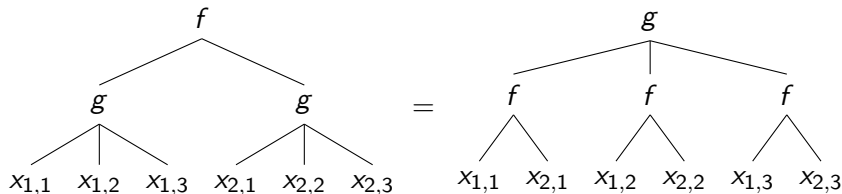


Monad:

$$A \mapsto S \rightarrow S \times A$$

Tensor

$$\langle \Sigma_1, E_1 \rangle \otimes \langle \Sigma_2, E_2 \rangle = \langle \Sigma_1 + \Sigma_2, \text{Th}(E_1 \cup E_2 \cup E_{\Sigma_1 \otimes \Sigma_2}) \rangle$$



Tensor with $\{\text{State, Reader, Writer}\}$ theory
 $\cong \{\text{State, Reader, Writer}\}$ monad transformer.

Monoid

Right Monoid Action $\langle S, M, \cdot \rangle$:

Set S , monoid M and a function

$$(\cdot) : S \times M \rightarrow S$$

compatible with the monoid operation:

$$s \cdot e = s \quad (s \cdot m) \cdot n = s \cdot (mn)$$

Idea

Generalised state \leftrightarrow Monoid actions

Generalised State Operations

For a monoid action $\langle M, S, \cdot \rangle$, $|S| = k > 0$:

lookup : $|S|$ **act**_{*m*} : 1

Generalised State Presentation

lookup $(\lambda s.x) = x$

Generalised State Presentation

lookup ($\lambda s.x$) = x **lookup** ($\lambda s.\text{lookup}(\lambda t.x_{s,t})$) = **lookup** ($\lambda r.x_{r,r}$)

Generalised State Presentation

lookup ($\lambda s.x$) = x **lookup** ($\lambda s.\text{lookup}(\lambda t.x_{s,t})$) = **lookup** ($\lambda r.x_{r,r}$)

act_m (**act_n** x) = **act_{mn}** x

Generalised State Presentation

lookup $(\lambda s.x) = x$ **lookup** $(\lambda s.\text{lookup}(\lambda t.x_{s,t})) = \text{lookup}(\lambda r.x_{r,r})$

act_m (**act**_n x) = **act**_{mn} x

act_e $x = x$

Generalised State Presentation

lookup $(\lambda s.x) = x$ **lookup** $(\lambda s.\text{lookup}(\lambda t.x_{s,t})) = \text{lookup}(\lambda r.x_{r,r})$

act_m $(\text{act}_n x) = \text{act}_{mn} x$ **act**_m **lookup** $(\lambda s.x_s) = \text{lookup}(\lambda r.\text{act}_m x_{r.m})$

act_e $x = x$

Generalised State Presentation

lookup $(\lambda s.x) = x$ **lookup** $(\lambda s.\text{lookup}(\lambda t.x_{s,t})) = \text{lookup}(\lambda r.x_{r,r})$

act_m $(\text{act}_n x) = \text{act}_{mn} x$ **act**_m **lookup** $(\lambda s.x_s) = \text{lookup}(\lambda r.\text{act}_m x_{r \cdot m})$

act_e $x = x$ **lookup** $(\lambda s.\text{act}_{m_s} x_s) = \text{lookup}(\lambda s.\text{act}_{n_s} x_s)$

provided for all s , $s \cdot m_s = s \cdot n_s$

Generalised State Presentation

lookup $(\lambda s. x) = x$ **lookup** $(\lambda s. \text{lookup} (\lambda t. x_{s,t})) = \text{lookup} (\lambda r. x_{r,r})$

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provided for all $s, s \cdot m_s = s \cdot n_s$

Back to Normal State

lookup $(\lambda s.x) = x$ **lookup** $(\lambda s. \text{lookup}(\lambda t.x_{s,t})) = \text{lookup}(\lambda r.x_{r,r})$

act_m $(\text{act}_n x) = \text{act}_{mn} x$ **act**_m **lookup** $(\lambda s.x_s) = \text{lookup}(\lambda r. \text{act}_m x_{r \cdot m})$

act_e $x = x$ **lookup** $(\lambda s. \text{act}_{m_s} x_s) = \text{lookup}(\lambda s. \text{act}_{n_s} x_s)$

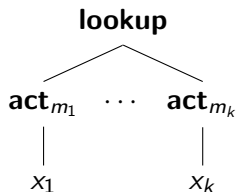
provided for all $s, s \cdot m_s = s \cdot n_s$

To recover state:

- ▶ Define associative operation on S : $s_1 \cdot s_2 := s_2$
- ▶ Lift to $\mathbb{M}_{\text{ow}} := \langle \{e\} + S, \cdot \rangle$, *overwrite monoid*.
- ▶ Global state is theory for following action over S :

$$\langle s_1, m \rangle \mapsto s_1 \cdot m$$

Normal Form



Free Model: Generalised State Monad

Orbit

For a monoid action $\langle M, S, \cdot \rangle$ and $s \in S$, the *orbit* of s is

$$sM := \{s \cdot m \mid m \in M\}$$

Generalised State Monad:

$$A \mapsto \prod_{s \in S} sM \times A$$

Useful?

Global State

Instantiating the overwrite monoid:

$$A \mapsto \prod_{s \in S} s\mathbb{M}_{\text{ow}} \times A = \prod_{s \in S} S \times A \cong S \rightarrow S \times A$$

Reader

Instantiating the trivial monoid:

$$A \mapsto \prod_{s \in S} s\{e\} \times A = \prod_{s \in S} \{s\} \times A \cong \prod_{s \in S} A \cong S \rightarrow A$$

What about Writer?

Marriage of Monads and Effects

Idea (Wadler):

For a monad T implementing effects \mathcal{E} :

Code using effects $\varepsilon \subseteq \mathcal{E}$ lives inside a monad T_ε .

Applications:

- ▶ Safety guarantees.
- ▶ Effect-dependent optimisations:
- ▶ Modular functional programming.

```
let x <= M in let y <= M in N
≡
```

```
let x <= M in let y <= x in N
```

for M in T_{lookup} or T_{upd}

Problem: **What's T_ε ?**

Conservative Restriction

Conservative Restriction $\langle \Sigma_1, E_1 \rangle \leftrightarrow \langle \Sigma_2, E_2 \rangle$:

$\Sigma_1 \subseteq \Sigma_2$ and $\forall s, t \in \Sigma_1$ -Terms:

$$E_2 \vdash s = t \iff E_1 \vdash s = t$$

Idea

Monad $T_\varepsilon \leftrightarrow$ Conservative restriction of T to ε

State Restrictions

To determine T_ε :

$$\varepsilon := \{\mathbf{lookup}, \mathbf{act}_{m_1}, \dots, \mathbf{act}_{m_n}\}$$

Define:

Generated Submonoid $[m_1, \dots, m_n]$:

Finite combinations from $\{m_1, \dots, m_n\}$.

Restricted Action $(\cdot)_\varepsilon$:

Same as (\cdot) , with elements from $[m_1, \dots, m_n]$.

Characterisation:

T_ε is the Generalised State theory for $(\cdot)_\varepsilon$.

Special Case: $T_{\{\mathbf{lookup}\}}$ is Reader.

State Restrictions

To determine T_ε :

$$\varepsilon := \{\mathbf{act}_{m_1}, \dots, \mathbf{act}_{m_n}\}$$

Define:

Indistinguishability:

$$m_1 \equiv m_2 \iff \forall s \in S : s \cdot m_1 = s \cdot m_2$$

M_ε :

The quotient $[m_1, \dots, m_n] / \equiv$.

Characterisation:

T_ε is Writer with M_ε .

Special Case: Writer M is $T_{\{\mathbf{act}_s | s \in S\}}$ for some faithful action.

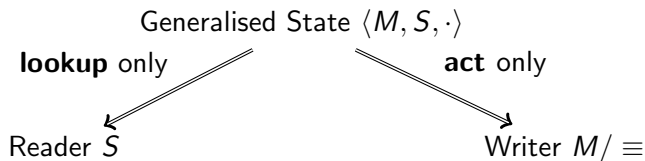
Generalised State Transformers

Let L be a theory with monad T .

The monad for $L \otimes$ Generalised-State is:

$$A \mapsto \prod_{s \in S} T(sM \times A)$$

- ▶ Algebraic theory of effects uncovered underlying structure:



- ▶ Unified semantic account for global state.
- ▶ Useful for programming?

Further work

- ▶ Larger work on semantics for type and effect systems.
- ▶ Generalising S from a set to CPO (or more general).

Image Sources

- ▶ Alfred Leete, *Kitchener Britons*, <http://commons.wikimedia.org/wiki/File:Kitchener-Britons.jpg>

Generalised State Monad Explicitly

Generalised State Monad:

$$A \mapsto \prod_{s \in S} sM \times A$$

$$\eta : a \mapsto \lambda s. \langle s, a \rangle$$

$$\mu : \lambda s. \langle s'_s, \lambda t. \langle t'_{s,t}, a_{s,t} \rangle \rangle \mapsto \lambda r. \langle t'_{r,s'_r}, a_{r,s'_r} \rangle$$