

# Algebraic Foundations for Type and Effect Analysis

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(another work in progress)

## Effect Systems

$$\Gamma \vdash M_i : A_i \mid \varepsilon_i$$

## Effect-Dependent Optimisations [Benton et al.]

$$\varepsilon_i \subseteq \{\text{lookup}\} \implies \begin{array}{c} \text{let } x = M_1 \text{ in } (\text{let } y = M_2 \text{ in } N) \\ \equiv \\ \text{let } y = M_2 \text{ in } (\text{let } x = M_1 \text{ in } N) \end{array}$$

## Difficulty

Change language  $\implies$  reprove from scratch.

## Solution

General semantic account of effect type systems.

## Tool

Algebraic theory of effects.

## Observation [Wadler]

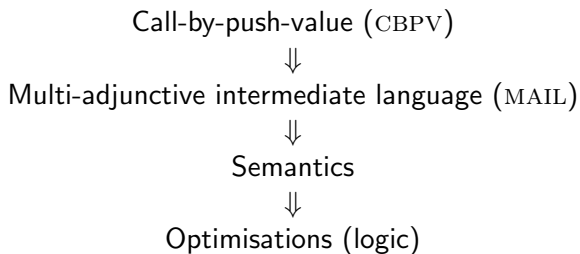
Change notation:

$$\Gamma \vdash M : T_{\varepsilon}A$$

$T_{\varepsilon}$  behaves like a monad.

## Our Idea

- ▶ Elements in  $\varepsilon$  are effect operations.
- ▶  $\varepsilon$  is the signature for  $T_{\varepsilon}$ .
- ▶ Which equations?

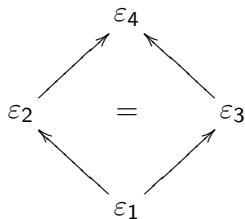


# Talk Structure

- ▶ Abstract, non-algebraic, view of theory.
  - ▶ MAIL
  - ▶ Semantics.
  - ▶ Digression: generalised handlers.
- ▶ Algebraic instantiation.
  - ▶ Algebraic MAIL
  - ▶ Semantics.
  - ▶ Conservative restriction models.
  - ▶ Calculating conservative restrictions.
- ▶ Optimisations
- ▶ Modular approximation model.
- ▶ Conclusions.

## Effect Hierarchy

Category  $\mathcal{E}$  with  $\varepsilon$  as objects. Typically partial order of effect sets.

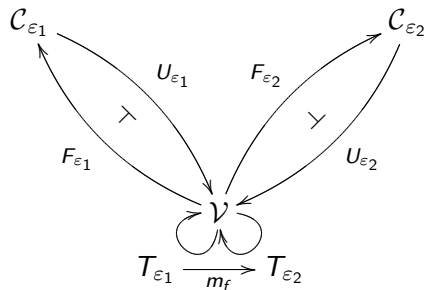


## $\mathcal{E}$ -MAIL

Multiple computation kinds  $\text{Comp}_{\mathcal{E}}$ , type constructors  $F_{\mathcal{E}}$  and  $U_{\mathcal{E}}$ .  
Explicit coercion along  $\mathcal{E}$  morphisms:

$$\frac{\Gamma \vdash_{\mathcal{E}_1} M : F_{\mathcal{E}_1} A}{\Gamma \vdash_{\mathcal{E}_2} \text{coerce}_{f:\mathcal{E}_1 \rightarrow \mathcal{E}_2} M : F_{\mathcal{E}_2} A}$$





## General Exceptional Syntax

$$\frac{\Gamma \vdash_{\varepsilon_1} M : F_{\varepsilon_1} A_1 \quad \vdash_h H : (A_9; \varepsilon_1) \Rightarrow (\underline{B}; \varepsilon_2) \quad \Gamma \vdash_v P : A_9 \quad \Gamma, x : A_1 \vdash_{\varepsilon_2} N : A_9 \rightarrow \underline{B}}{\Gamma \vdash_{\varepsilon_2} \text{try } M \text{ with } H @ P \text{ as } x \text{ in } N : \underline{B}}$$

## Semantics

$\llbracket \underline{B} \rrbracket \in \mathcal{C}_{\varepsilon_2}$ ,  $\llbracket H \rrbracket \in \mathcal{C}_{\varepsilon_1}$ :

$$U_{\varepsilon_2}(\llbracket \underline{B} \rrbracket^{[A_9]}) \cong U_{\varepsilon_1} \llbracket H \rrbracket$$

## General Exceptional Syntax

$$\frac{\Gamma \vdash_{\varepsilon_1} M : F_{\varepsilon_1} A_1 \quad \vdash_h H : (A_0; \varepsilon_1) \Rightarrow (\underline{B}; \varepsilon_2) \quad \Gamma \vdash_v P : A_0 \quad \Gamma, x : A_1 \vdash_{\varepsilon_2} N : A_0 \rightarrow \underline{B}}{\Gamma \vdash_{\varepsilon_2} \text{try } M \text{ with } H @ P \text{ as } x \text{ in } N : \underline{B}}$$

## Semantics

$[[\underline{B}]] \in \mathcal{C}_{\varepsilon_2}, [[H]] \in \mathcal{C}_{\varepsilon_1}$ :

$$U_{\varepsilon_2} ([[B]]^{[A_0]}) \cong U_{\varepsilon_1} [[H]]$$

## Examples

- ▶ Exception handlers.
- ▶ Logging.
- ▶ Effect reification.

## Integrated Effects

Overall effect equational theory  $\mathcal{L} = \langle \Sigma, E \rangle$ .

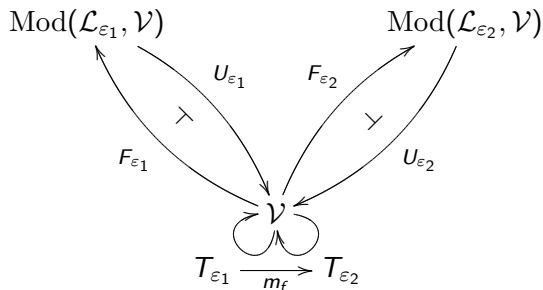
Effect hierarchy  $\mathcal{E}$  a partial order of subsets  $\varepsilon \subseteq \Sigma$ .

$$\frac{\Gamma \vdash_V V:A_2 \quad \Gamma \vdash_\varepsilon M:A_1 \rightarrow \underline{B}}{\Gamma \vdash_\varepsilon \text{op}_V M:\underline{B}} \quad \text{op}:A_1 \rightarrow A_2 \in \varepsilon$$

## Semantics

$$\begin{array}{ccc} \Sigma_{\varepsilon_1} & \xrightarrow{\Sigma_{\varepsilon_1 \subseteq \varepsilon_2}} & \Sigma_{\varepsilon_2} \\ \downarrow & = & \downarrow \\ \mathcal{L}_{\varepsilon_1} & \xrightarrow{G_{\varepsilon_1 \subseteq \varepsilon_2}} & \mathcal{L}_{\varepsilon_2} \end{array}$$

# Derived Semantics



## Benchmark Model

$$\mathcal{L}_\varepsilon := \mathcal{L}$$

- 👍 Original meaning.
- 👎 Discards effect analysis.

## Relating Models

Logical relations for comparing other models against benchmark.

## Conservative Restriction

$\mathcal{L}_\varepsilon :=$  all terms over  $\varepsilon$ , and  $\mathcal{L}$  equations between them.

Categorically:

$$\begin{array}{ccc} \Sigma_\varepsilon & \hookrightarrow & \Sigma \\ \text{full} \downarrow & = & \downarrow \\ \mathcal{L}_\varepsilon & \xrightarrow{\text{faithful}} & \mathcal{L} \end{array}$$

- 👍 Original meaning.
- 👍 Uses effect analysis.
- 👎 Finding  $\mathcal{L}_\varepsilon$  is non-trivial.

## Idea

Restrictions of  $\mathcal{L} = \mathcal{L}^1 \circ \mathcal{L}^2$  in terms of component restrictions.

## Sum Theorem

For consistent finitary Lawvere theories:

$$(\mathcal{L}^1 + \mathcal{L}^2)_{\varepsilon_1 + \varepsilon_2} = \mathcal{L}_{\varepsilon_1}^1 + \mathcal{L}_{\varepsilon_2}^2$$

## Tensor Counterexample

Eckmann-Hilton:

$$(\text{Monoids} \otimes \text{Monoids})_{\{\cdot, 1\} + \emptyset} = \text{Commutative Monoids}$$

In particular:  $x \cdot y = y \cdot x$



## Observation

In practice:


**Sum:** Free theories.

**Tensor:** Global state, reader and writer.

## Our Idea

Analyse restrictions in these cases only.

 Works in **Set**.

 Subtle in  $\omega$ **CPO**: Works for the above theories, but may fail for others (non-determinism).

## Validity

$\mathcal{M} \models M = N \iff \llbracket M \rrbracket = \llbracket N \rrbracket \text{ in } \mathcal{M}.$

## Cataloguing Optimisations

For existing transformations:

- ▶ Validate.
- ▶ Classify.
- ▶ Generalise.

## Structural

- ▶  $\beta, \eta$  rules.
- ▶ Sequencing.
- ▶ Coercion, e.g.:

$$\text{coerce}_f(\text{coerce}_g M) = \text{coerce}_{f \circ g} M$$

- ▶ Handlers:
  - ▶  $\beta$ :  $\text{try}(\text{return}_\varepsilon V)$  with  $H @ P$  as  $x$  in  $N = N[V/x] \cdot P$  (Pretnar's thesis)
  - ▶ More can be said for user-defined handlers.
  - ▶ Others?

## Algebraic

Equations in the underlying Lawvere theory, e.g.:

$$\text{update}_V(\text{lookup}(N)) = \text{update}_V N'V$$

# Optimisation Taxonomy

## Abstract

Monadic properties of  $\mathcal{C}_\varepsilon$  yield optimisations, e.g. **discard**:

$$\frac{T_\varepsilon \text{ affine} \quad \Gamma \vdash_\varepsilon M : F_\varepsilon A \quad \Gamma \vdash_{\varepsilon'} N : B}{\Gamma \vdash_{\varepsilon'} (\text{coerce}_f M) \text{ to } x \text{ in } N = N}$$

## Algebraic View

When  $T_\varepsilon$  is algebraic:

$$T_\varepsilon \text{ affine} \iff \begin{array}{c} f \\ \diagdown \quad \diagup \\ x \quad \cdots \quad x \end{array} = x \quad (\text{absorption law holds})$$



Assists recognition.



Modularity of combination.

# More [Abstract Optimisations]

## Copy Optimisation

$$\frac{T_\varepsilon \text{ relevant} \quad \Gamma \vdash_\varepsilon M : F_\varepsilon A \quad \Gamma, x:A, y:A \vdash_{\varepsilon'} N : \underline{B}}{(\text{coerce}_f M) \text{ to } x \text{ in } (\text{coerce}_f M) \text{ to } y \text{ in } N = (\text{coerce}_f M) \text{ to } x \text{ in } N[x/y]}$$

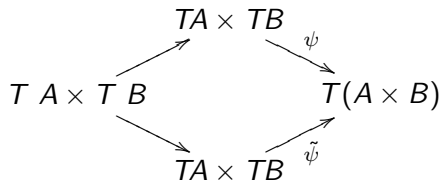
## Algebraic View

Relevant  $\iff$

$$\begin{array}{c} f \\ / \quad \backslash \\ f \quad \dots \quad f \\ / \backslash \quad \quad \quad / \backslash \\ x_{00} \dots x_{0n} \quad x_{n0} \dots x_{nn} \end{array} = \begin{array}{c} f \\ / \quad \backslash \\ x_{00} \dots x_{nn} \end{array} \quad (\text{idempotency})$$

## Definition

**Commutative** monad  $T$ :



## Definition

**Commuting** monad morphisms  $T_1 \rightarrow T \leftarrow T_2$ :

$$\begin{array}{ccc} & TA \times TB & \\ & \nearrow & \searrow \psi \\ T_1A \times T_2B & & T(A \times B) \\ & \searrow & \nearrow \tilde{\psi} \\ & TA \times TB & \end{array}$$



## Commute Optimisation

$$\begin{array}{c} T_{\varepsilon_1} \xrightarrow{m_1} T_\varepsilon \xleftarrow{m_2} T_{\varepsilon_2} \text{ commute} \\ \Gamma \vdash_{\varepsilon_i} M_i : F_{\varepsilon_i} A_i \quad \Gamma, x_1 : A_1, x_2 : A_2 \vdash_\varepsilon N : \underline{B} \\ \hline (\text{coerce}_{f_1} M_1) \text{ to } x_1 \text{ in } (\text{coerce}_{f_2} M_2) \text{ to } x_2 \text{ in } N = \\ (\text{coerce}_{f_2} M_2) \text{ to } x_2 \text{ in } (\text{coerce}_{f_1} M_1) \text{ to } x_1 \text{ in } N \end{array}$$

## Algebraic View

$m_1$  translations commute with  $m_2$  translations.

## Corollary

$T_1 \rightarrow T_1 \otimes T_2 \leftarrow T_2$  commute.

## Hoist Optimisation

$$\frac{T_e = \text{id} \quad \Gamma \vdash_\varepsilon M : F_\varepsilon A \quad \Gamma, x:A \vdash_{\varepsilon'} N : \underline{B}}{\text{return}_\varepsilon (\text{thunk}_{\varepsilon'} ((\text{coerce}_f M) \text{ to } x \text{ in } N)) = M \text{ to } x \text{ in } (\text{return}_\varepsilon (\text{thunk}_{\varepsilon'} N))}$$

## Caveats

- ▶ Generalise?
- ▶ Algebraic view?

## Modular Approximation Model

e.g.:

$$\mathcal{L} := \mathcal{L}^1 + (\mathcal{L}^2 \otimes \mathcal{L}^3)$$




with  $\mathcal{L}^i \sim \langle \Sigma_i, E_i \rangle$ .

Approximation model, with  $\varepsilon_1^i + \varepsilon_2^i + \varepsilon_3^i \subseteq \Sigma^1 + \Sigma^2 + \Sigma^3$ :

$$\begin{array}{ccc} & \mathcal{L}_{\varepsilon_1^4}^1 + (\mathcal{L}_{\varepsilon_2^4}^2 \otimes \mathcal{L}_{\varepsilon_3^4}^3) & \\ & \nearrow & \nwarrow \\ \mathcal{L}_{\varepsilon_1^2}^1 + (\mathcal{L}_{\varepsilon_2^2}^2 \otimes \mathcal{L}_{\varepsilon_3^2}^3) & = & \mathcal{L}_{\varepsilon_1^3}^1 + (\mathcal{L}_{\varepsilon_2^3}^2 \otimes \mathcal{L}_{\varepsilon_3^3}^3) \\ & \nwarrow & \nearrow \\ & \mathcal{L}_{\varepsilon_1^1}^1 + (\mathcal{L}_{\varepsilon_2^1}^2 \otimes \mathcal{L}_{\varepsilon_3^1}^3) & \end{array}$$

# Relating Models

Approximation Model  $\models M = N \implies$  Benchmark Model  $\models M = N$

-  Modularity.
-  Equational soundness.
-  Approximation only.

## Conclusions

- ▶ Algebraically directed research.
- ▶ Modular account.
- ▶ A general account, in ascending degree.

## Further work

- ▶ Effect reconstruction.
- ▶ More  $\omega$ **CPO**.
- ▶ Logical relations.
- ▶ Handlers.
- ▶ Rewriting.
- ▶ More optimisations?
- ▶ Atkey's permissions.
- ▶ More effects.
- ▶ Concurrency.
- ▶ Presheaf models.