

# An introduction to ProbProg

Ohad Kammar  
University of Edinburgh  
and  
Denotational Limited

Huawei Tech-Talk



14 January 2021



THE UNIVERSITY of EDINBURGH

**informatics ifcs**

Laboratory for Foundations  
of Computer Science



supported by:

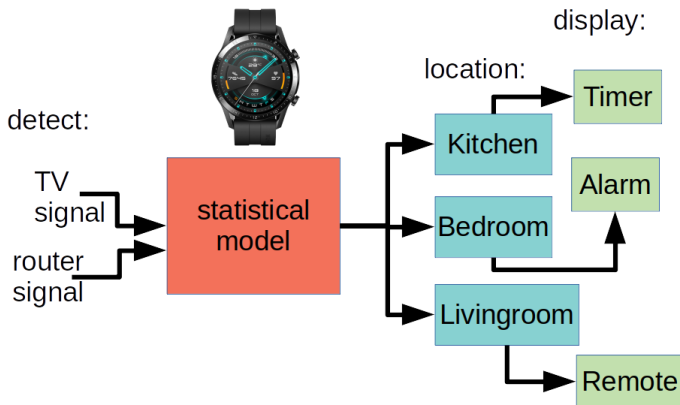


THE ROYAL  
SOCIETY

The  
Alan Turing  
Institute

Facebook Research

# Spatial-context inference



# Spatial-context inference

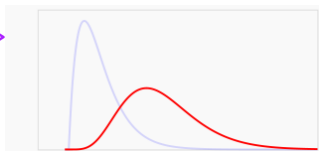
```
data Location = Kitchen|Livingroom|Bedroom|Study|Bath
data Device = TV | Fridge | Router | Printer | Tablet
type SensorData = (Device, Double)
```

```
dataset :: [SensorData]
dataset = [(Fridge, 3.25)
          , (TV      , 2.25)
          , (Router  , 3.25)
          , (Tablet  , 1.75)]
```

# Spatial-context inference

```
data Location = Kitchen|Livingroom|Bedroom|Study|Bath
data Device = TV | Fridge | Router | Printer | Tablet
type SensorData = (Device, Double)
```

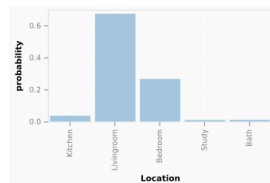
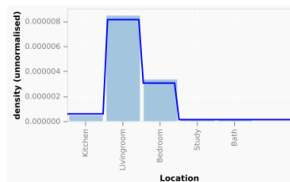
```
dataset :: [SensorData]
-- condition:  $d \sim \Gamma(x, 1.0)$ 
proximity :: Double -> Double -> Dist ()
proximity d x = condition(d, gammaDistr x 1.0)
-- condition: devices from close in dataset are close
closeTo :: [SensorData] -> [Device] -> Dist ()
closeTo dataset close = do
  forM dataset $ \ (dev, dist) ->
    if dev `elem` close
    then proximity 2.0 dist
    else proximity 6.0 dist
  pure ()
```



density of  $\Gamma(2.0, 1.0)$   
and  $\Gamma(6.0, 1.0)$

# Spatial-context inference

```
dataset :: [SensorData]
-- condition:  $d \sim \Gamma(x, 1.0)$ 
proximity :: Double -> Double -> Dist ()
-- condition: devices from close in dataset are close
closeTo :: [SensorData] -> [Device] -> Dist ()
spatialModel :: [SensorData] -> Dist Location
spatialModel dataset = do
  loc <- uniformD locations
  dataset `closeTo` case loc of
    Kitchen    -> [Fridge]
    Livingroom -> [TV, Router]
    Bedroom    -> [Tablet]
    Study      -> [Printer]
    Bath       -> []
  return loc
```



- ▶ Meaningful with small data  
Data can be expensive
- ▶ Model is descriptive  
Accessible to domain experts
- ▶ Deals with missing data  
**Printer** was missing
- ▶ Quantifies uncertainty  
Uncertainty is mathematically meaningful
- ▶ Application-embedded  
Stay within ecosystem, personal data stays on device

# What is ProbProg?

- ▶ Machine interpretable statistical modelling
- ▶ ProbProg = PL + sampling + conditioning + inference
- ▶ common language for:
  - ▶ domain experts
  - ▶ algorithmic statisticians
  - ▶ performance engineers
  - ▶ computer

# Talk Structure

- ▶ ProbProg “Hello, World!”
- ▶ What are we computing?
- ▶ Inference: compilation schemes for ProbProg

Apology: many ProbPLs out there,  
we'll mention only a few

Request: only a few slides, so  
so please interact!

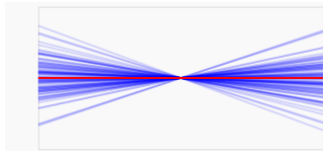


# “Hello, World!”

## Homogeneous linear regression

```
model :: Dist (Double -> Double)
model = do
  a <- normal 0.0 1.0
  let f x = a * x
  condition (f 2.0, normal 6.0 0.25)
  return f
```

Prior:



Posterior:

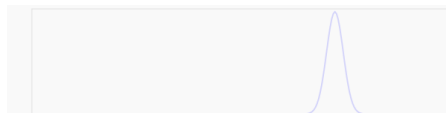


$$\text{prior} \in \text{Dist} (X \times \Theta) \quad \xrightarrow{\text{Hypothesis}} \quad H \in \text{Dist} \Theta \ni \theta$$

$$\text{prior} \in \text{Dist} ((\mathbb{R} \rightarrow \mathbb{R}) \times \mathbb{R}) \quad \xrightarrow{\text{Hypothesis}} \quad H \in \text{Dist} \mathbb{R} \ni \theta$$

Bayes's Law: posterior  $\propto \frac{d\theta}{dH} \cdot \text{prior}$

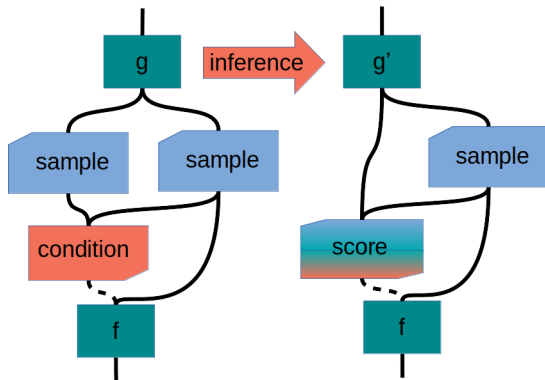
hypothesis and observation density wrt Lebesgue



density of observation wrt hypothesis

What are we computing?

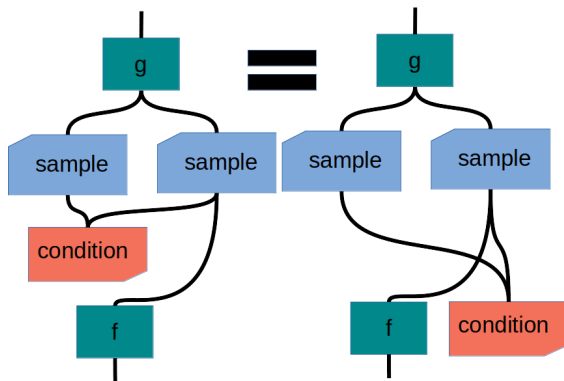
(for compiler engineers)



Invariant:  $\frac{d\theta}{dH} \cdot \text{prior}$

What are we computing?

(for compiler engineers)



Invariant:  $\frac{d\theta}{dH} \cdot \text{prior}$

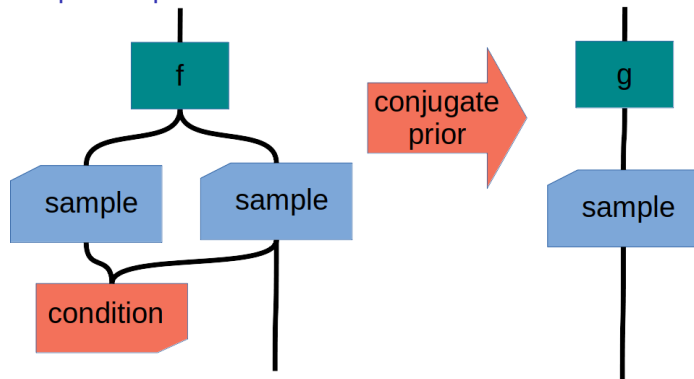
# Why is it difficult?

$$\frac{d\theta}{dH} \cdot \text{prior} = \lambda f \cdot \int_X \text{prior}(dx dt) \frac{d\theta}{dH}(t) \cdot f(x)$$

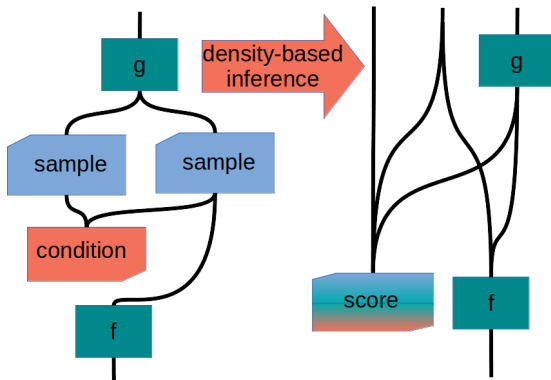
- ▶ integrals are hard!
- ▶ correct densities need care
- ▶ each fragment is an arbitrary (pure) program!
- ▶ correct answer isn't always clear

# Compilation schemes

## Peephole optimisations

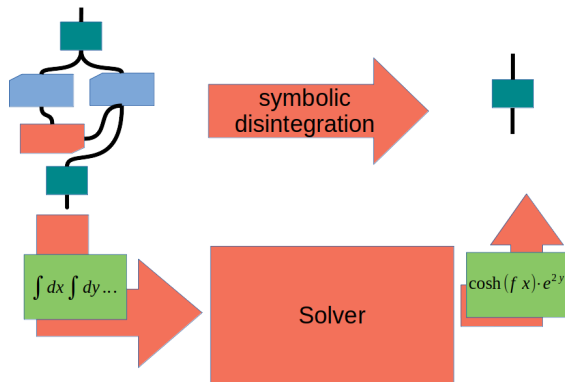


# Compilation schemes



E.g.: Stan, SlicStan + enumeration of discrete variables  
[Gorinova et al. POPL'19, and ongoing work]

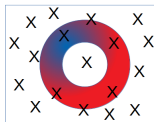
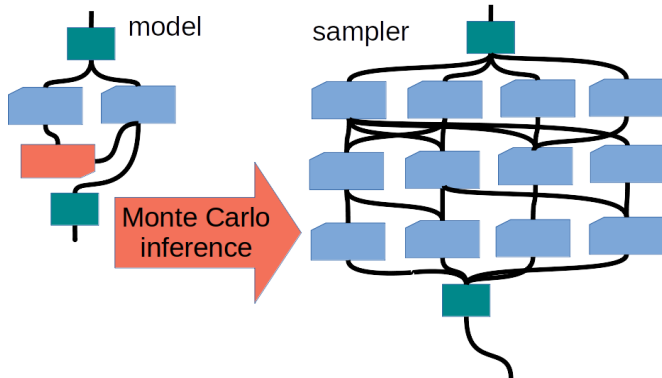
# Compilation schemes



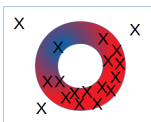
Hakaru [Narayanan et al. FLOPS'16]  
Psi [Gehr-Misailovic-Vechev, CAV'16]



# Compilation schemes



Baseline:  
importance  
sampling



statistically  
efficient  
sampling

Most systems. Anglican and Church  
are purely Monte Carlo

## No silver bullet!

- ▶ Inference is non-computable [Ackerman-Freer-Roy LICS'11]
- ▶ Steps towards bespoke inference:
  - ▶ Pyro: non-standard interpretations (effect handlers)
  - ▶ Monad-Bayes: modular inference building blocks (monad transformers)
  - ▶ Gen: Programmable inference (guides)

- ▶ ProbProg; machine-readable formalism for statistical modelling
- ▶ Key features:
  - ▶ Meaningful with small data
  - ▶ Model is descriptive
  - ▶ Deals with missing data
  - ▶ Quantifies uncertainty
  - ▶ Application-embedded
- ▶ Non-computable: need bespoke inference