

Handlers in Action

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Higher-Order Programming and Effects (HOPE)

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joint with

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Exception handlers

```
handle
  if (get  $\ell$ ) = 0
  then raise DivideByZero
  else 42 / (get  $\ell$ )
with
  DivideByZero  $\mapsto$  0
  e  $\mapsto$  raise e

return  $x \mapsto$  display  $x$ 
```

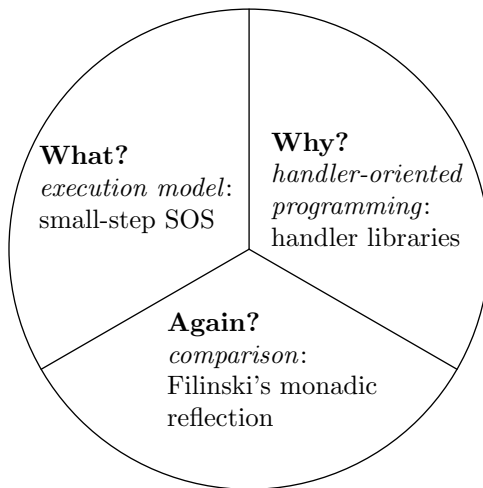
```
handle  
  if (get  $\ell$ ) = 0  
  then raise DivideByZero  
  else 42 / (get  $\ell$ )  
with  
  raise DivideByZero  $k \mapsto 0$   
  raise  $e$   $k \mapsto$  raise  $e$   
  get  $/$   $k \mapsto k(1)$   
  return  $x \mapsto$  display  $x$ 
```

Addressed questions



Contribution

- functional language with handlers
- sound type-and-effect system

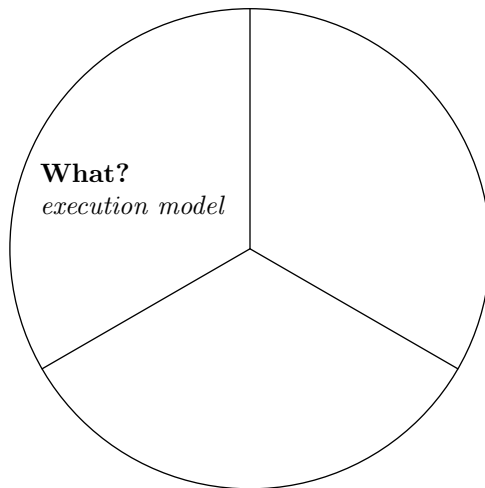


Two implementation techniques:

- free monads in Haskell;
- (delimited) control operators in SML and Racket;

Goal

Facilitate operational discussion.



Algebraic effects

Operations, parameter types, arities

$$\text{op} : Pa \rightarrow Ar$$

For example:

$$\text{lookup} : Loc \rightarrow Integer$$
$$\text{update} : (Loc, Integer) \rightarrow Unit$$
$$\text{raise} : Exception \rightarrow Empty$$

Usage

$$\text{op } V (\lambda x \rightarrow M)$$

For example:

$$\text{lookup } \ell (\lambda i \rightarrow \text{update } (\ell, i + 1) (\lambda_ \rightarrow ()))$$

Algebraic effects (cntd.)

Generic effects

Another familiar variant:

$$\text{gen } V = \text{op } V (\lambda x \rightarrow x)$$

For example:

```
get  $\ell$       = lookup  $\ell$  ( $\lambda i \rightarrow i$ )  
set ( $\ell, i$ ) = update ( $\ell, i$ ) ( $\lambda _ \rightarrow ()$ )  
raise  $e$     = raise  $e$  ( $\lambda z \rightarrow \text{whatever } z$ )
```


Syntax

- ▶ Value terms V
- ▶ Computation terms

$$M ::= \dots \mid \text{op } V (\lambda x \rightarrow M) \mid \mathbf{handle } M \mathbf{ with } H$$

- ▶ Handlers

$$H ::= \text{op } p \ k \mapsto M$$
$$\dots$$
$$\mathbf{return } x \mapsto N$$

For example:

```
raise DivideByZero  $k \mapsto 0$ 
raise  $e$   $k \mapsto \text{raise } e$ 
lookup  $l$   $k \mapsto k(1)$ 
return  $x \mapsto \text{display } x$ 
```

Reduction rules

handle

if (get ℓ) = 0

then raise *DivideByZero*

else 42 / (get ℓ)

with

raise *DivideByZero* $k \mapsto 0$

raise $e \quad k \mapsto \text{raise } e$

lookup $l \quad k \mapsto k(1)$

return $x \mapsto \text{display } x$

Reduction rules

```
handle  
  if (lookup  $\ell$   
      ( $\lambda i \rightarrow i$ ))  
    = 0  
  then  $M_1$   
  else  $M_2$   
with  $H$ 
```

Reduction rules

handle		handle
if (lookup ℓ		lookup ℓ ($\lambda i \rightarrow$
($\lambda i \rightarrow i$))	$\xrightarrow{\text{hoist}}$	if i
$= 0$		$= 0$
then M_1		then M_1
else M_2		else M_2
with H)
		with H

More generally:

$$\mathcal{H}[\text{op } V (\lambda x \rightarrow M)] \xrightarrow{\text{hoist}} \text{op } V (\lambda x \rightarrow \mathcal{H}[M])$$

for hoisting frames $\mathcal{H}[-]$ with $x \notin FV(\mathcal{H})$.

Reduction rules (cntd.)

handle

lookup ℓ ($\lambda i \rightarrow$

if $i = 0$

then M_1

else M_2

)

with

...

lookup l $k \mapsto k$ (1)

($\lambda i \rightarrow$

handle

if $i = 0$

then M_1

else M_2

with H

) (1)

$\xrightarrow{\text{op}}$

More generally, for handler H satisfying $x \notin FV(H)$:

handle op V ($\lambda x \rightarrow M$)

with

...

op p $k \mapsto N$

...

$\xrightarrow{\text{op}} N[V/p, (\lambda x \rightarrow \text{handle } M \text{ with } H)/k]$

Reduction rules (cntd.)

$$\begin{array}{ccc} (\lambda i \rightarrow & & \\ \quad \textbf{handle} & & \\ \quad \quad \textbf{if } i = 0 & & \\ \quad \quad \textbf{then } M_1 & \xrightarrow{\beta}_* & \textbf{handle } M_2 \textbf{ with } H \\ \quad \quad \textbf{else } M_2 & & \\ \quad \textbf{with } H & & \\) (1) & & \end{array}$$

Reduction rules (cntd.)

handle
 42 / (get ℓ)
with H $\xrightarrow{\text{hoist, op, } \beta, \text{ arithmetic}}^*$ **handle** 42 **with** H

Reduction rules (cntd.)

handle 42 with
...
return $x \mapsto \text{display } x$ $\xrightarrow{\text{handler return}}$ **display 42**

More generally:

handle V with
...
return $x \mapsto N$ $\xrightarrow{\text{handler return}}$ $N [V / x]$

Type-and-effect system

- ▶ Value types $A, B ::= \dots \mid U_E C$.
- ▶ Computation types C .
- ▶ Effect signatures: (with P_a and A_r value types)

$$E ::= \{\text{op} : P_a \rightarrow A_r, \dots\}$$

- ▶ Handlers

$$R ::= A \overset{E}{\Rightarrow}^{E'} C$$

Type-and-effect system (cntd.)

- ▶ Value type judgements $\Gamma \vdash V : C$.
- ▶ Computation type judgements $\Gamma \vdash_E M : C$:

$$\frac{\Gamma \vdash V : Pa \quad \Gamma, x : Ar \vdash_E M : C}{\Gamma \vdash_E \text{op } V (\lambda x \rightarrow M) : C} (\text{op} : Pa \rightarrow Ar \in E)$$

$$\frac{\Gamma \vdash_E M : FA \quad \Gamma \vdash H : A \xRightarrow{E}^{E'} C}{\Gamma \vdash_{E'} \text{handle } M \text{ with } H : C}$$

Type-and-effect system (cntd.)

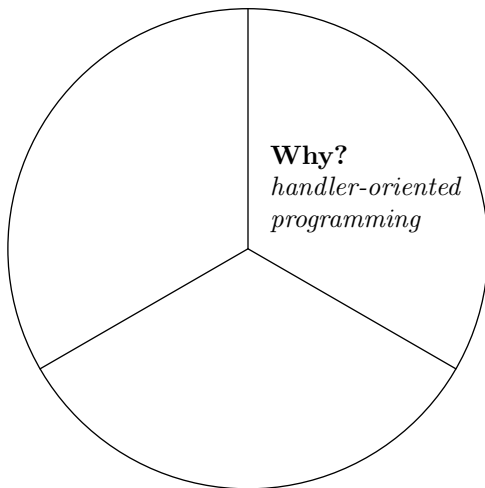
- ▶ Handler type judgements $\Gamma \vdash H : R$:

$$\frac{\begin{array}{c} \Gamma, p : Pa, k : U_E(Ar \rightarrow C) \vdash_E M : C \\ \dots \\ \Gamma, x : A \vdash_E N : C \end{array}}{\Gamma \vdash_{\text{op}} p \ k \mapsto M} \quad \dots$$
$$\text{return } x \mapsto N : A \{ \text{op} : Pa \rightarrow Ar, \dots \} \Rightarrow^E C$$

Note the placement of E's.

Type soundness

If $\vdash_{\{\}} M : FA$ then $M \rightarrow^* \text{return } V$, for $\vdash V : A$.



User-defined effects

In Haskell

```
m = do  
  fruit ← chooseFruit  
  form ← chooseForm  
  return $ form ++ fruit
```

Individually:

```
bothFruit :: [String]  
bothFruit = ["apple", "orange"]  
randomForm :: IO String  
randomForm = do  
  x ← getStdRandom random  
  if x then return "raw "  
    else return "cooked "
```

User-defined effects

In Haskell

```
m = do  
  fruit ← chooseFruit  
  form ← chooseForm  
  return $ form ++ fruit
```

Combined:

```
result :: IO [String]  
result = runListT m  
chooseFruit = ListT $ return bothFruit  
chooseForm = lift    $ randomForm
```

Handler-oriented programming

Horizontal composition

```
handle (do
    fruit  $\leftarrow$  chooseFruit
    form  $\leftarrow$  chooseForm
    return $ form  $\text{++}$  fruit)
(ChooseFruit  $\mapsto$  ( $\lambda p\ k \rightarrow$  do xs  $\leftarrow$  k "apple"
    ys  $\leftarrow$  k "orange"
    return (xs  $\text{++}$  ys))  $\triangleleft$ 
ChooseForm  $\mapsto$  ( $\lambda p\ k \rightarrow$  do { v  $\leftarrow$  randomForm; k v })  $\triangleleft$ 
Empty,
 $\lambda x \rightarrow$  return [x])
```

Handler-oriented programming

Vertical composition

```
handleListProbV :: IO [String]
handleListProbV =
  handle
    (handle do
      fruit ← chooseFruit
      form ← chooseForm
      return $ form ++ fruit)
    (ChooseFruit ↦
      (λp k → do xs ← k "apple"
                  ys ← k "orange"
                  return (xs ++ ys)) ◁ ChooseForm ◁ Empty,
      λx → return [x]))
    (ChooseForm ↦ (λp k → do { v ← randomForm; k v }
      ◁ Empty, return)
```


Handler-oriented programming

Evaluation

Is it better than monads? We don't know!

Bauer's thesis [private communication]

My experience with eff convinces me that we have

$$\begin{aligned} \text{"effects + handlers"} &: \text{"delimited continuations"} \\ &= \\ \text{"while"} &: \text{"goto"} \end{aligned}$$

Our contribution

Facilitate investigation: libraries in Haskell, SML, and Racket.

Implementation: free monads

Concretely

For $E = \{\text{raise} : \text{Exception} \rightarrow \text{Empty}, \text{lookup} : \text{Loc} \rightarrow \text{Integer}\}$:

```
data Comp a = Return a
           | Raise Exception
           | Lookup (Loc, Integer → Comp a)
```

Consequently:

```
raise e      = Raise e
lookup ℓ m   = Lookup (ℓ, m)
```

```
handle (Return a)      raiseC lookupC returnC = returnC a
handle (Raise e)       raiseC lookupC returnC = raiseC e
handle (Lookup (ℓ, m)) raiseC lookupC returnC = lookupC ℓ m
```

Implementation: free monads (cntd.)

Typed implementation:

Option 1

Use dynamic types and casts:

data *Comp* *a* = *Return* *a* | *App* (*Op*, *Dyn*, *Dyn* \rightarrow *Comp* *a*)

Implementation: free monads (cntd.)

Option 2

Use GADTs and proxy types:

```
data Comp e a ::  $\star$  where  
  Ret :: a  $\rightarrow$  Comp e a  
  App :: Witness op e  $\rightarrow$  op  $\rightarrow$  Param op  $\rightarrow$   
        (Arity op  $\rightarrow$  Comp e a)  $\rightarrow$  Comp e a
```

- ▶ More expressive types (effect polymorphism)
 \implies code reuse.
- ▶ Technicalities suggest *row polymorphisms* as more suitable.

Get it from:

<https://github.com/slindley/effect-handlers>

Implementation: delimited control

Primitive control operators

shift0, **reset0**:

$$\mathbf{reset0} (\mathcal{E}[\mathbf{shift0} (\lambda k \rightarrow M)]) \rightarrow M [(\lambda x \rightarrow \mathbf{reset0} (\mathcal{E}[x])) / k]$$

Compare with the derived:

$$\begin{aligned} \mathbf{handle} \mathcal{H}[\text{op } V (\lambda x \rightarrow M)] \mathbf{with} \dots \text{op } p \ k \mapsto N \dots \\ \rightarrow N [V / p, (\lambda x \rightarrow \mathbf{handle} \mathcal{H}[M] \mathbf{with} H) / k] \end{aligned}$$

Implementation: delimited control (cntd.)

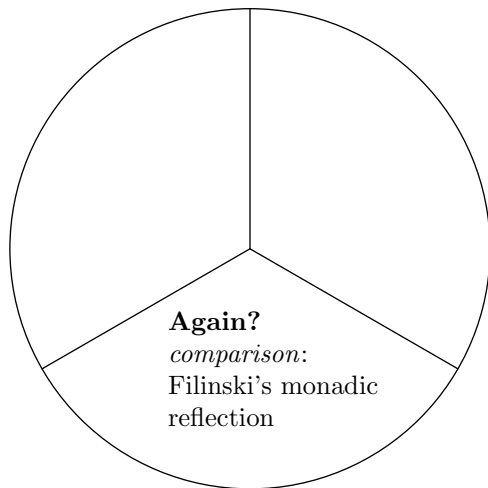
The **handle** construct **handle** M **with** H

- ▶ *push* current effect operation bindings from H onto a stack.
- ▶ **reset0** (M)

Effect operation $\text{op } V (\lambda x \rightarrow M)$

- ▶ **shift0** captures the hoisting context, concatenating it with M
- ▶ use the effect binding from top of the stack to execute op

and **return** is straightforward.



Conclusion

- Adequacy
- Non-free effects

What?

execution model:
SOS, sound effect
system

Why?

*handler-oriented
programming:*
expressive
implementations

- Evaluation
- Dynamic effect generation
- Performance

Again?

comparison:
Filinski's monadic
reflection

- delimited control

Try it, and join the discussion!

Images

- ▶ `http://www.agriaffaires.co.uk/img_583/telescopic-handler/telescopic-handler.jpg`
- ▶ `http://ginavivinetto.files.wordpress.com/2008/09/chelsea-handler.jpg`